



## **BAMS UAS & Global Hawk Joint Efficiencies**

### **2011 Department of Defense Maintenance Symposium and Exhibition**

**Presented by:**

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Joint Efficiencies IPT Lead, PMA-262**

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# BLUF (Bottom Line Up Front)

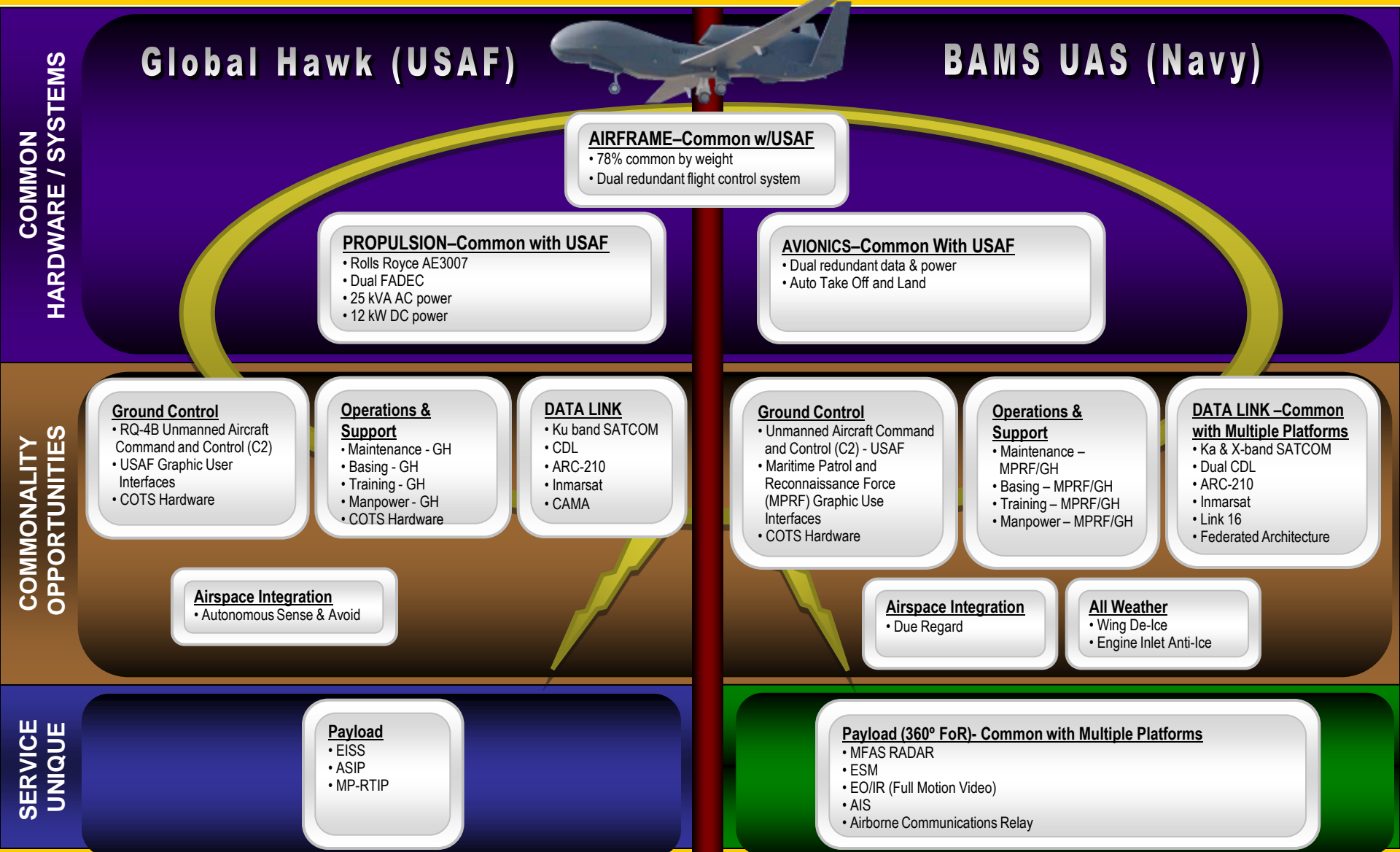
Persistent Maritime Unmanned Aircraft Systems Program Office

- **Navy BAMS UAS and AF Global Hawk programs pursuing efforts to enable interoperability/commonality to increase operational effectiveness and reduce total ownership cost**



# GH/BAMS UAS Commonality (2009)

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COMMON HARDWARE / SYSTEMS

## Global Hawk (USAF)

## BAMS UAS (Navy)

### AIRFRAME—Common w/USAF

- 78% common by weight
- Dual redundant flight control system

### PROPULSION—Common with USAF

- Rolls Royce AE3007
- Dual FADEC
- 25 kVA AC power
- 12 kW DC power

### AVIONICS—Common With USAF

- Dual redundant data & power
- Auto Take Off and Land

COMMONALITY OPPORTUNITIES

### Ground Control

- RQ-4B Unmanned Aircraft Command and Control (C2)
- USAF Graphic User Interfaces
- COTS Hardware

### Operations & Support

- Maintenance - GH
- Basing - GH
- Training - GH
- Manpower - GH
- COTS Hardware

### DATA LINK

- Ku band SATCOM
- CDL
- ARC-210
- Inmarsat
- CAMA

### Ground Control

- Unmanned Aircraft Command and Control (C2) - USAF
- Maritime Patrol and Reconnaissance Force (MPRF) Graphic Use Interfaces
- COTS Hardware

### Operations & Support

- Maintenance – MPRF/GH
- Basing – MPRF/GH
- Training – MPRF/GH
- Manpower – MPRF/GH

### DATA LINK –Common with Multiple Platforms

- Ka & X-band SATCOM
- Dual CDL
- ARC-210
- Inmarsat
- Link 16
- Federated Architecture

### Airspace Integration

- Autonomous Sense & Avoid

### Airspace Integration

- Due Regard

### All Weather

- Wing De-Ice
- Engine Inlet Anti-Ice

SERVICE UNIQUE

### Payload

- EISS
- ASIP
- MP-RTIP

### Payload (360° FoR)- Common with Multiple Platforms

- MFAS RADAR
- ESM
- EO/IR (Full Motion Video)
- AIS
- Airborne Communications Relay



# GH/BAMS UAS Commonality (2010)

Persistent Maritime Unmanned Aircraft Systems Program Office



## Global Hawk (USAF)

## BAMS UAS (Navy)

COMMON  
HARDWARE / SYSTEMS

**PROPULSION**

- Rolls Royce AE3007H
- Dual FADEC
- AC generator
- DC generator

**AVIONICS**

- Dual redundant data & power
- Auto Take Off and Land

**AIRFRAME**

Dual redundant flight control system

**AUTONOMOUS AIRBORNE SENSE & AVOID**

- Radar for Airborne Sense and Avoid
- Software for Autonomous Sense and Avoid

**GROUND SYSTEM**

- Core Architecture

COMMONALITY  
OPPORTUNITIES

**Ground System**

- RQ-4B Unmanned Aircraft Command and Control (C2)
- USAF Graphic User Interfaces
- COTS Hardware

**Operations & Support**

- Maintenance – GH
- Basing – GH
- Training – GH
- Manpower – GH
- COTS Hardware

**Communication**

- Ku band SATCOM
- CDL
- ARC-210
- Inmarsat
- CAMA

**Ground System**

- Unmanned Aircraft Command and Control (C2) – USAF
- Maritime Patrol & Reconnaissance Force (MPRF) Graphic Use Interfaces
- COTS Hardware

**Operations & Support**

- Maintenance – MPRF/GH
- Basing – MPRF/GH
- Training – MPRF/GH
- Manpower – MPRF/GH

**Communication-Common with Multiple Platforms**

- Ka & X-band SATCOM
- Dual CDL
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**All Weather**

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SERVICE  
UNIQUE

**Payload**

- EISS
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**Payload (360° FoR)- Common with Multiple Platforms**

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# GH/BAMS UAS Commonality (2009-2010 JROC through Current Plan)

Persistent Maritime Unmanned Aircraft Systems Program Office

## Global Hawk (USAF)

## BAMS UAS (Navy)

COMMON  
HARDWARE / SYSTEMS

### Operations & Support

- Maintenance – MPRF/GH
- Basing – MPRF/GH
- Training – MPRF/GH
- Manpower – MPRF/GH

### AIRFRAME

- Dual redundant flight control system

### Communication-Common with Multiple Platforms

- Dual CDL
- ARC-210
- Inmarsat
- Link 16
- Federated Architecture

### PROPULSION

- Rolls Royce AE3007H
- Dual FADEC
- 25 kVA AC power
- 12 kW DC power

### AVIONICS

- Dual redundant data & power
- Auto Take Off and Land

### PROPULSION

- Rolls Royce AE3007H
- Dual FADEC
- 25 kVA AC power / 30 kVA AC power
- 12 kW DC power

### GROUND SYSTEM

- Core Architecture

COMMONALITY  
OPPORTUNITIES

### Ground System

- RQ-4B Unmanned Aircraft Command and Control (C2)
- USAF Graphic User Interfaces
- COTS Hardware

### Operations & Support

- Maintenance - GH
- Basing - GH
- Training - GH
- Manpower - GH
- COTS Hardware

### Communication

- Ku band SATCOM
- CDL
- ARC-210
- Inmarsat
- CAMA

### Ground System

- Core Architecture
- Unmanned Aircraft Command and Control (C2) - USAF
- Maritime Patrol & Reconnaissance Force (MPRF) Graphic Use Interfaces
- COTS Hardware

### Operations & Support

- Maintenance – MPRF/GH
- Basing – MPRF/GH
- Training – MPRF/GH
- Manpower – MPRF/GH

### Ground System

- Unmanned Aircraft Command and Control (C2) - USAF
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### AUTONOMOUS AIRBORNE SENSE & AVOID

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### Comms

Ka & Ku-band SATCOM

### Payload (360° FoR)- Common with Multiple Platforms

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- Airborne Communications Relay

### Comms

Ka & X-band SATCOM

MOA signed between PMA-262 and 303d AESG and Endorsed by PEO (U&W) and USAF ASC Executive Director



# Cost Avoidance Achieved

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- **Software**
  - **Approximately \$25M cost avoidance realized in GH code reuse**
  - **Approximately \$380M cost avoidance realized in total code reuse across OSD portfolio (Overall 77% software reuse)**
- **Engine**
  - **Leveraging commercial heritage and GH growth engine investment (Approximately \$20M in cost avoidance)**
- **AF engine made available for BAMS fit checks**
- **Production**
  - **Block load share savings**
  - **Tooling**
  - **Learning curve**





# BAMS & GLOBAL HAWK Synergy MOA

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**GH/BAMS Synergies MOA, Signed June 2010**  
Specifies USN/USAF working groups to “Identify and incorporate every appropriate synergy in basings, maintenance, aircraft Command and Control (C2), training, logistics, and data requirements for Processing, Exploitation, and Dissemination (PED) functions.”

**#1 – Deliver interoperable systems to the warfighter to achieve mission success**

- Identify BAMS/GH operations requiring unique systems
- Develop rapid and efficient system response
- Develop simplified logistics trail
- Maximize the number of interoperable systems for mission flexibility

**#2 – Save money and resources where possible**

- Eliminate redundant effort
- Reduce personnel footprint requirement
- Combine similar operations
- Maximize common configurations

Program Offices and Synergies Working Group finds optimum solutions for USN/USAF interoperability



# Joint Concept Tenets

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- The following are necessary for maximum long-term efficiency:
  - Common Ground Station (CGS)
  - Organic Maintenance
  - Joint Maintenance – merge AFI & OPNAV practices
  - Common Technical Publications
  - Joint Launch and Recovery Operations
  - Joint Training – some synergies exist (MST/WST)
- JConcept provides direction for follow-on studies





# Joint Concept Details

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- JConcept draft addresses Joint opportunities for :
  - CONUS and OCONUS Basing
  - Manning and Organizational structures
  - Training (pilot and maintenance)
  - Equipment (Common Ground Station, tools, support equipment)
  - Maintenance practices (common curriculum, training sites, and procedures)
  - Facilities
  - Operations (Launch & Recovery, BLOS, maintenance)
  - Other DOTMLPF actions (e.g., manpower studies)



# GH / BAMS Basing Synergies

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# BAMS UAS Manpower and Personnel (Current)

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- BAMS UAS
  - NAVAIR and the Navy Manpower Analysis Center developed Preliminary Squadron Manning Document (PSQMD) to facilitate fleet integration; source document for MS C Manpower Estimate Report (MER)
  - BAMS UAS PSQMDs developed 24 September 2010
- USAF
  - Using Contractor Logistic Support
  - Global Hawk maintenance uses a total force concept for manpower & personnel support, supported by active duty, ANG, AFR, and contract personnel
  - Peacetime environment two of the three FOLs (PACOM and EUCOM) will be supported by contractor maintenance. Personnel rotating out of Beale AFB support CENTCOM
  - The Global Hawk manpower estimate provided by ACC/A8U and ACC is based on twenty-four (24) Primary Mission Aircraft Inventory (PMAI)



# BAMS UAS Manpower and Personnel (Future)

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- Program offices exploring future manpower and personnel requirements and constructs
  - Working with Synergy Working Group concepts team to define possible future constructs
  - Air Force exploring transition to blue suit maintenance
  - Navy and Air Force exploring formation and construct of organizational units to support forward operating bases



# Training Synergy Approach

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- Operator Training
  - Initial Qualification Training for pilots/AVOs at Beale AFB
  - Synergy opportunity for remainder of aircrew and pilot/AVO MQT limited by differences in mission and aircraft sensors
  - MPRF synergy leveraged for Sensor Operator / Tactical Coordinator (USN) training at NAS Jacksonville
- Maintenance Training
  - Co-located maintenance training facility at Beale AFB
  - Initial training targeted for FY17 with incremental phasing of courses
  - Consists of initial training tracks for GH Block 20 and MQ-4C UAS
  - Delta courses provided for cross-training GH to MQ-4C UAS



# Training Devices

## Persistent Maritime Unmanned Aircraft Systems Program Office

- Common Mission Systems Trainer
  - Embedded trainer based on Navy MST
  - Incorporates AF crew training requirements
- Common Pilot Trainer
- Full Mission Simulation for individuals/crews
- Joint and Fleet Synthetic Training
- Embedded in Mission Control System
  - Redundant MCS side will be used for training
- Standalone FRS MST planned for next contract phase
- Sensor Simulations
- Aircraft Simulation – Closed Loop Simulation
- Contains both trainee terminal and scenario recording capabilities (Audio, Video, Truth Data)





# Common Ground Station (CGS)

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- **CGS allows USN and USAF to fly each other's UAs**
  - **LOS L&R**
  - **BLOS Transit / Ferry**
  - **Emergencies**





# CGS Challenges

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- UCI = Additional scope – Impact unknown
- DMS = Initial Capability (Early Fielding)
  - Meeting DMS need date forcing GSRA to look at Initial Capability (ICAP) or early fielding initiative
    - GH GSRA Block 20/30 ICAP Initiative
      - GS infrastructure and multi-block C2 capability ready for flight test in 2013
      - Original development strategy delayed flight testing until 2014
      - Accelerate GH Block 20/30 capability flight test for risk reduction



- JCWG and JCET working towards
  - Common Pilot/AVO display content
    - Initial list developed and under refinement
  - Common moving map
    - Study in work - recommendation 11 April
  - Common operator station (hardware) configuration
    - Study completed 10 March
    - CGS execution to incorporate configuration defined
  - Sensor Operator configuration not evaluated



# Logistics Planning

## Persistent Maritime Unmanned Aircraft Systems Program Office

- Navy Business Case Analysis will inform depot decision and serve as basis for Performance Based Logistics (PBL) solution
  - Navy engaging in Depot Source of Repair Analysis
  - Navy to coordinate with Air Force for teaming on depot and possible PBL solutions in all appropriate areas
  - Logistics Synergy Working Group established
  - Common maintenance hub planned for Beale to accommodate all O level + maintenance requirements
- Air Force Logistics Plans
  - 2 Level Maintenance concept; organizational and depot
  - Combined Contractor Logistics with organic depot support by 2016
  - Organic depot studies and Business Case Analysis by 3rd QFY 2012
  - Depot support is provided by OEM; DMAWG process



- BAMS and GH teams realizing synergies across the programs
- Program offices working with Synergies Working Group and the operators to determine where potential for commonalities exist
- MOA structure in place to ensure areas of commonality can be acted upon by program offices expeditiously



# Questions

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